

# Constraint Composite Graph-Based Lifted Message Passing for Distributed Constraint Optimization Problems

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# Summary

For solving distributed constraint optimization problems (DCOPs), we develop CCG-Max-Sum, a distributed variant of the lifted min-sum message passing algorithm (Xu et al. 2017) based on the Constraint Composite Graph (Kumar 2008). We experimentally showed that CCG-Max-Sum outperformed other competitors.

# Agenda

- Distributed Constraint Optimization Problems (DCOPs)
- The Constraint Composite Graph (CCG)
- CCG-Max-Sum
  - Max-Sum and CCG-Max-Sum
  - The Nemhauser-Trotter (NT) Reduction
- Experimental Evaluation
- Conclusion and Future Work

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# Distributed Constraint Optimization Problems (DCOPs): Motivation

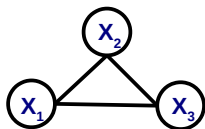
Cooperative multi-agent system interact to optimize a shared goal. This can be elegantly characterized by DCOPs (Modi et al. 2005; Yeoh et al. 2012).

- Coordination and resource allocation (Léauté et al. 2011; Miller et al. 2012; Zivan et al. 2015)
- Sensor networks (Farinelli et al. 2008)
- Device coordination in smart homes (Fioretto et al. 2017; Rust et al. 2016)

# Distributed Constraint Optimization Problems (DCOPs)

- There are  $N$  agents  $\mathbf{A} = \{a_1, a_2, \dots, a_N\}$ , each of which controls one or more variables in  $\mathbf{X} = \{X_1, X_2, \dots, X_N\}$ , specified by a mapping function  $\alpha$ . No single variable is controlled by two agents.
- Each variable  $X_i$  has a discrete-valued domain  $D_i$ .
- There are  $M$  cost functions (constraints)  $\mathbf{F} = \{f_1, f_2, \dots, f_M\}$ .
- Each cost function  $f_i$  specifies the cost for each assignment  $a$  of values to a subset  $\mathbf{x}^{f_i}$  of the variables (denoted by  $f_i(a|\mathbf{x}^{f_i})$ ).
- Find an optimal assignment  $a = a^*$  of values to these variables so as to minimize the total cost:  $f(a) = \sum_{i=1}^M f_i(a|\mathbf{x}^{f_i})$ .
- Known to be NP-hard.

# DCOP Example on Boolean Variables



$X_1$	
0	0.7
1	0.2

$X_2$	
0	0.3
1	0.8

$X_3$	
0	0.1
1	1.0

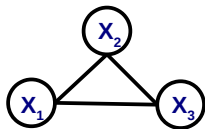
$X_1$	$X_2$	
	0	1
0	0.5	0.6
1	0.7	0.3

$X_2$	$X_3$	
	0	1
0	0.6	1.3
1	1.0	1.1

$X_1$	$X_3$	
	0	1
0	0.4	0.9
1	0.7	0.8

$$f(X_1, X_2, X_3) = f_1(X_1) + f_2(X_2) + f_3(X_3) + f_{12}(X_1, X_2) + f_{13}(X_1, X_3) + f_{23}(X_2, X_3)$$

# DCOP Example: Evaluate the Assignment $X_1 = 0, X_2 = 0, X_3 = 1$



$X_1$	
0	0.7
1	0.2

$X_2$	
0	0.3
1	0.8

$X_3$	
0	0.1
1	1.0

$X_1$	$X_2$	
	0	1
0	0.5	0.6
1	0.7	0.3

$X_2$	$X_3$	
	0	1
0	0.6	1.3
1	1.0	1.1

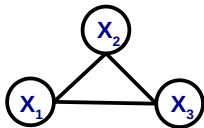
$X_1$	$X_3$	
	0	1
0	0.4	0.9
1	0.7	0.8

$$f(X_1 = 0, X_2 = 0, X_3 = 1) = 0.7 + 0.3 + 1.0 + 0.5 + 1.3 + 0.9 = 4.7$$

(This is not an optimal solution.)



## DCOP Example: Evaluate the Assignment $X_1 = 1, X_2 = 0, X_3 = 0$



$X_1$	
0	0.7
1	0.2

$X_2$	
0	0.3
1	0.8

$X_3$	
0	0.1
1	1.0

$X_1$	$X_2$	
	0	1
0	0.5	0.6
1	0.7	0.3

$X_2$	$X_3$	
	0	1
0	0.6	1.3
1	1.0	1.1

$X_1$	$X_3$	
	0	1
0	0.4	0.9
1	0.7	0.8

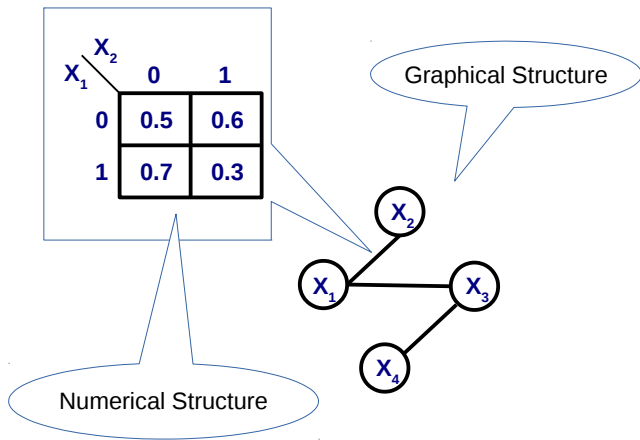
$$f(X_1 = 1, X_2 = 0, X_3 = 0) = 0.2 + 0.3 + 0.1 + 0.7 + 0.6 + 0.7 = 2.6$$

This is an optimal solution. Using brute force, it requires exponential time to find.

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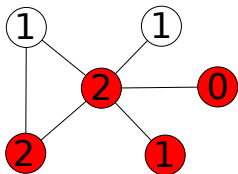
# Two Forms of Structure in DCOPs



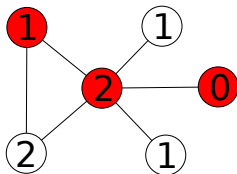
- Graphical: Which variables are in which cost functions?
- Numerical: How does each cost function relate the variables in it?

How can we exploit both forms of structure computationally?

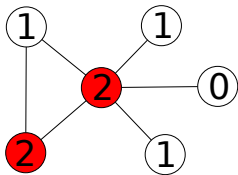
# Minimum Weighted Vertex Cover (MWVC)



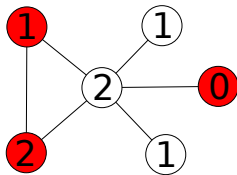
(a) ✗



(b) ✓



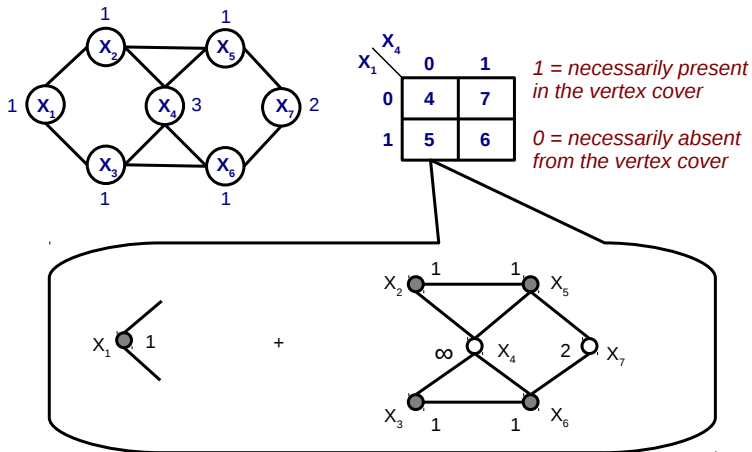
(c) ✗



(d) ✗

Each vertex is associated with a non-negative weight. Sum of the weights on the vertices in the vertex cover is minimized.

# Projection of Minimum Weighted Vertex Cover onto an Independent Set



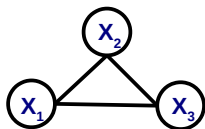
(Kumar 2008, Fig. 2)

# Projection of MWVC onto an Independent Set

Assuming Boolean variables in DCOPs

- Observation: The projection of MWVC onto an independent set looks similar to a cost function.
- Question 1: Can we build the lifted graphical representation for any given cost function? This is answered by (Kumar 2008).
- Question 2: What is the benefit of doing so?

# Lifted Representation: Example



$X_1$	
0	0.7
1	0.2

$X_2$	
0	0.3
1	0.8

$X_3$	
0	0.1
1	1.0

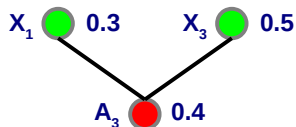
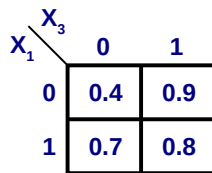
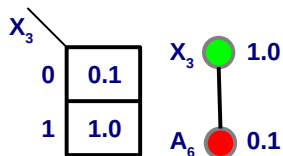
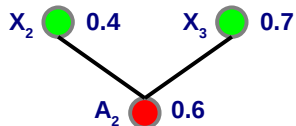
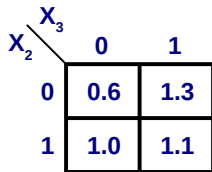
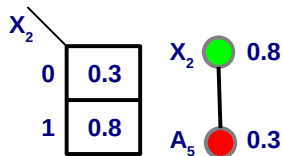
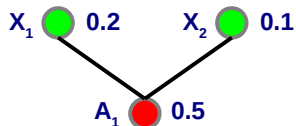
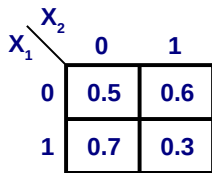
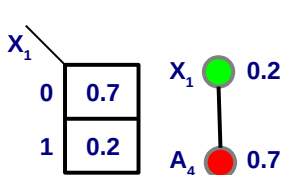
$X_1 \backslash X_2$	0	1
0	0.5	0.6
1	0.7	0.3

$X_2 \backslash X_3$	0	1
0	0.6	1.3
1	1.0	1.1

$X_1 \backslash X_3$	0	1
0	0.4	0.9
1	0.7	0.8

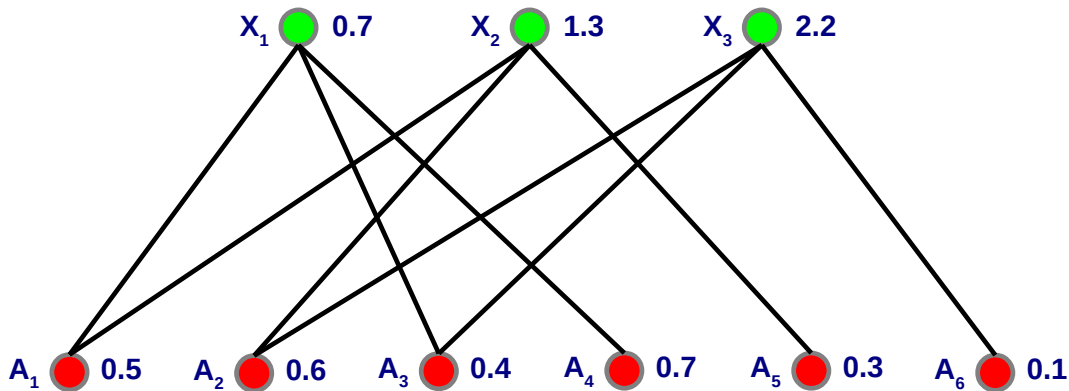
$$f(X_1, X_2, X_3) = f_1(X_1) + f_2(X_2) + f_3(X_3) + f_{12}(X_1, X_2) + f_{13}(X_1, X_3) + f_{23}(X_2, X_3)$$

# Lifted Representations: Example

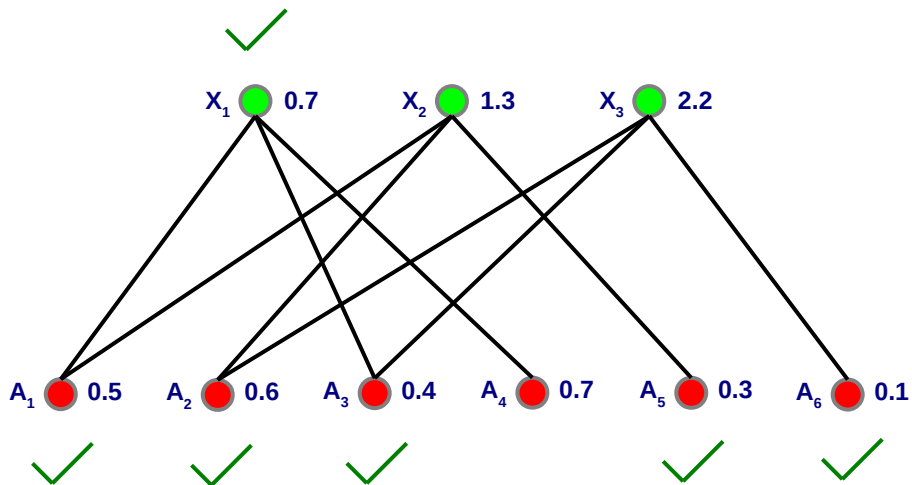




# Constraint Composite Graph (CCG)



## MWVC on the Constraint Composite Graph (CCG)



An MWVC of the CCG encodes an optimal solution of the original DCOP!

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# Max-Sum and CCG-Max-Sum

- Max-Sum (Farinelli et al. 2008; Stranders et al. 2009)
  - is a distributed variant of belief propagation
  - has information passed locally between variables and constraints
- CCG-Max-Sum Algorithm
  - Perform message passing iterations on the MWVC problem instance of the CCG
  - Messages are passed between adjacent vertices
  - Is a distributed variant of the lifted min-sum message passing algorithm (Xu et al. 2017)
- Despite the names, since our goal is to minimize the total cost, all **max** operators are replaced by **min** operators.

# Operations on Tables: Min

$$\min_{X_1} \left\{ \begin{array}{c|cc} & X_2 & \\ \hline X_1 & & \\ \hline 0 & 1 & 2 \\ 1 & 4 & 3 \end{array} \right\}$$

=

$X_1 \backslash$	
0	1
1	3

# Operations on Tables: Sum

$X_1 \backslash X_2$	0	1
0	1	2
1	4	3

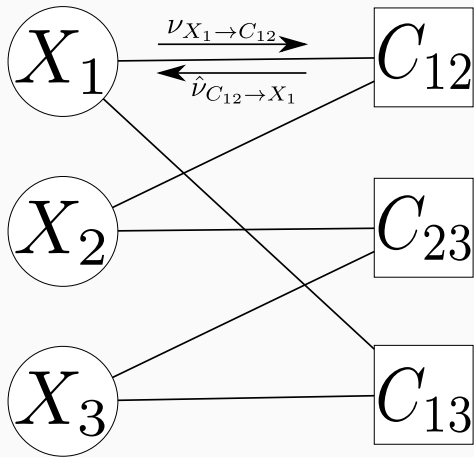
+

$X_1 \backslash X_2$	
0	5
1	6

=

$X_1 \backslash X_2$	0	1
0	$1 + 5 = 6$	$2 + 5 = 7$
1	$4 + 6 = 10$	$3 + 6 = 9$

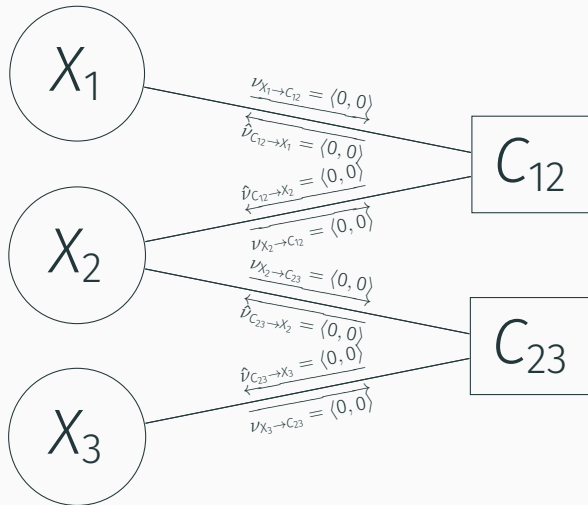
# Max-Sum



- A message is a table over the single variable, which is the sender or the receiver.
- A vertex of  $k$  neighbors
  1. applies **sum** on the messages from its  $k - 1$  neighbors and internal cost function, and
  2. applies **min** on the summation result and sends the resulting table to its  $k^{\text{th}}$  neighbor.



# Max-Sum



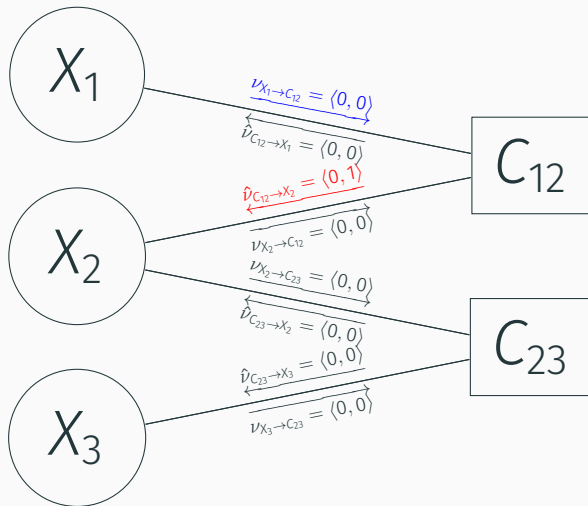
$X_1 \backslash X_2$	0	1
0	2	3
1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



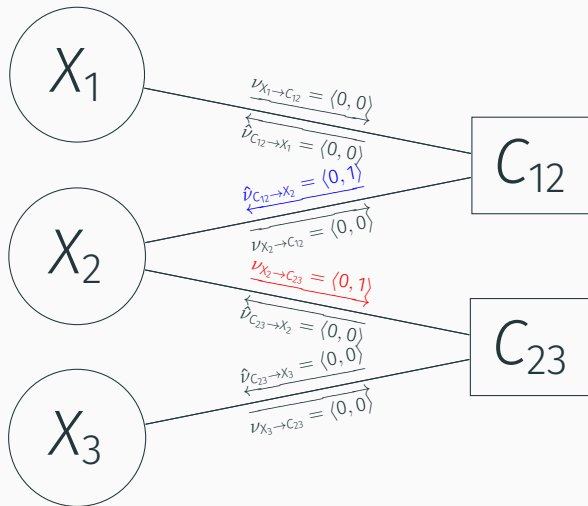
$X_1 \backslash X_2$	0	1
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1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
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1	2	2

(b)  $C_{23}$

# Max-Sum



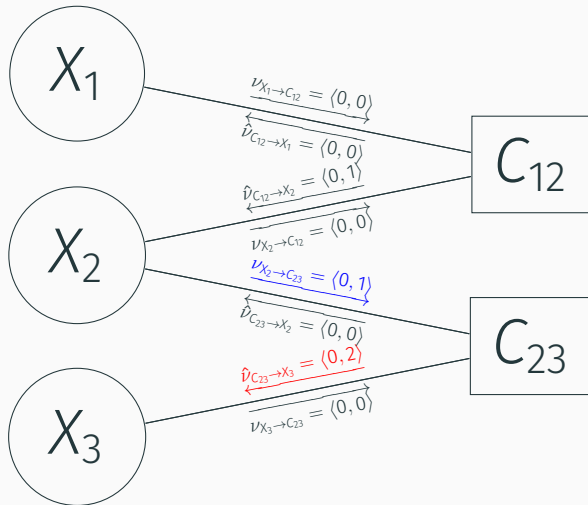
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1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



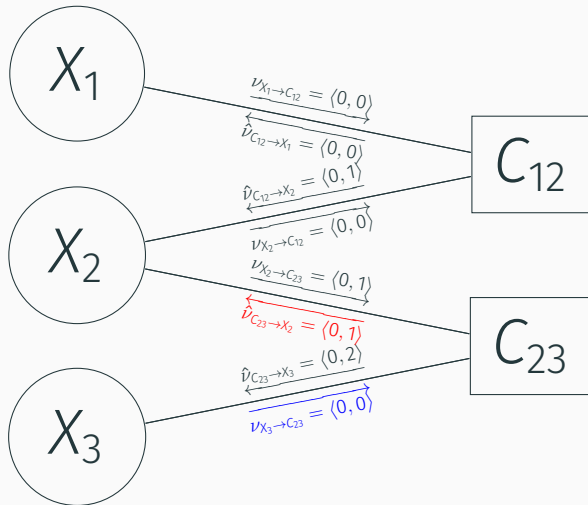
$X_1 \backslash X_2$	0	1
0	2	3
1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



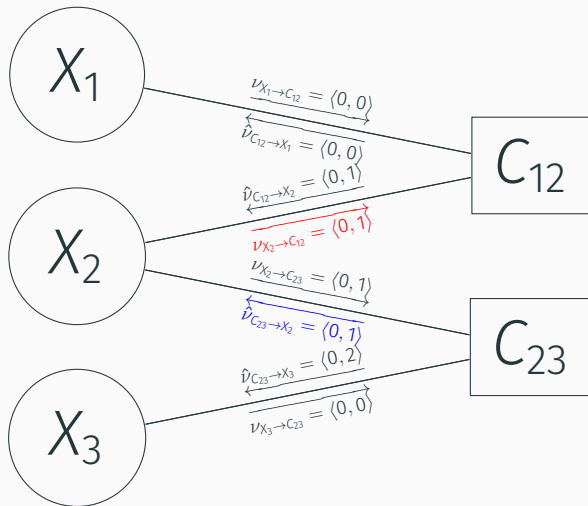
$X_1 \backslash X_2$	0	1
0	2	3
1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



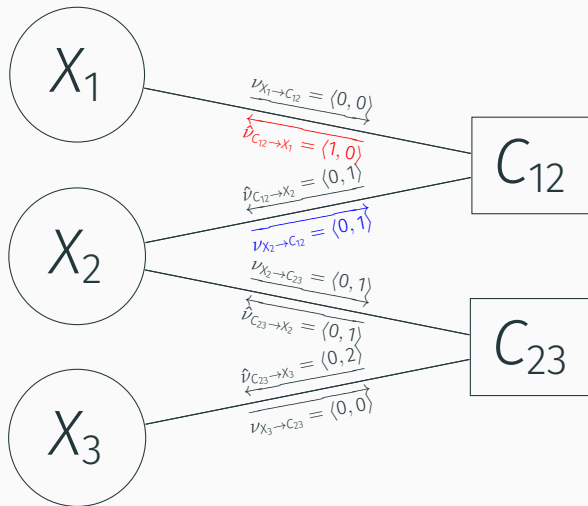
$X_1 \backslash X_2$	0	1
0	2	3
1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



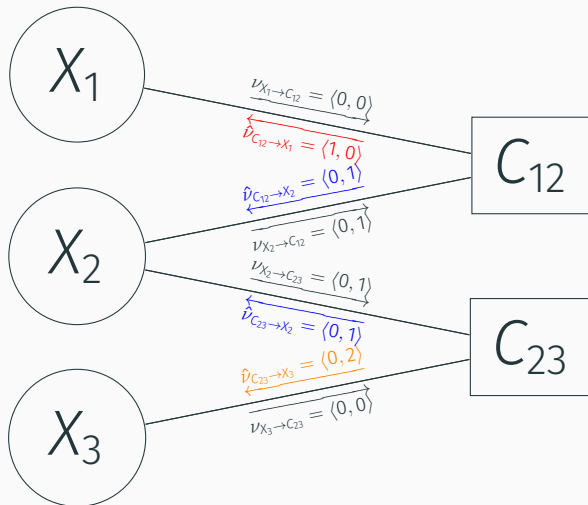
$X_1 \backslash X_2$	0	1
0	2	3
1	1	2

(a)  $C_{12}$

$X_2 \backslash X_3$	0	1
0	1	4
1	2	2

(b)  $C_{23}$

# Max-Sum



- $X_1 = 1$  minimizes  $\hat{\nu}_{C_{12} \rightarrow X_1}(X_1)$
- $X_2 = 0$  minimizes  $\hat{\nu}_{C_{12} \rightarrow X_2}(X_2) + \hat{\nu}_{C_{23} \rightarrow X_2}(X_2)$
- $X_3 = 0$  minimizes  $\hat{\nu}_{C_{23} \rightarrow X_3}(X_3)$
- Optimal solution:  
 $X_1 = 1, X_2 = 0, X_3 = 0$



## CCG-Max-Sum: Finding an MWVC on the CCG

- Treat MWVC problems on the CCG as DCOPs and apply Max-Sum on them.
- Messages are simplified passed between adjacent vertices.

$$\mu_{u \rightarrow v}^i = \max \left\{ w_u - \sum_{t \in N(u) \setminus \{v\}} \mu_{t \rightarrow u}^{i-1}, 0 \right\},$$

# Agenda

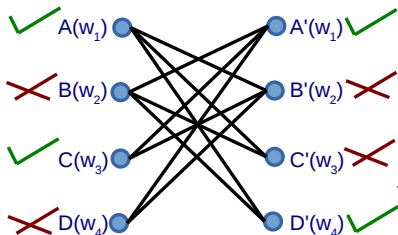
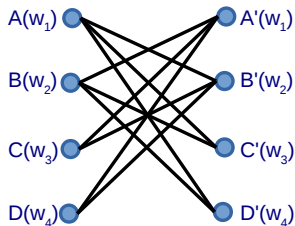
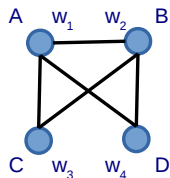
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# Motivation: Kernelization and the Nemhauser-Trotter Reduction



- The MWVC problem is known to be NP-hard.
- To solve such a problem, an algorithm that reduces the size of the problem in polynomial time is desirable.
- A kernelization method is one such algorithm.
- The Nemhauser-Trotter (NT) Reduction is one kernelization method for the MWVC problem.
- The Constraint Composite Graph enables the use of the NT reduction.

# The Nemhauser-Trotter (NT) Reduction



A is in the minimum weighted VC

B is not in the minimum weighted VC

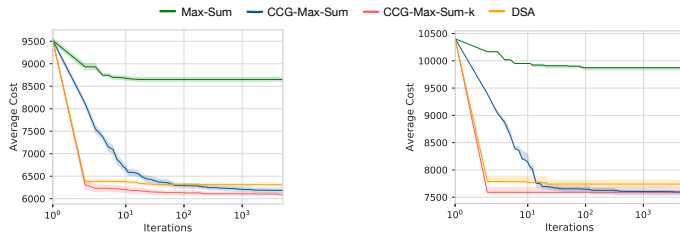
C and D are in the Kernel

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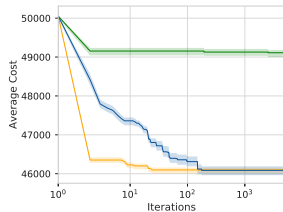
# Experimental Setup

- Algorithms
  - CCG-Max-Sum
  - CCG-Max-Sum-k: CCG-Max-Sum + NT reduction
  - Max-Sum (Farinelli et al. 2008; Stranders et al. 2009)
  - DSA (Zhang et al. 2005)
- Benchmark instances
  - Grid networks (2-d  $10 \times 10$  grids)
  - Scale-free networks (Barabási-Albert model (Barabási et al. 1999)),  
 $m = m_0 = 2$
  - Random networks (Erdős-Rényi model (Erdős et al. 1959)),  $p_1 = 0.4$  and  
 $p_1 = 0.8$ , max arity = 4
  - 30 benchmark instances in each instance set, 100 agents/variables
  - Costs are uniformly random numbers from 1 to 100.

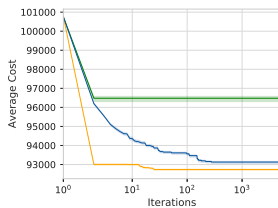


(a) grid networks

(b) scale-free networks



(c) low density random networks ( $p_1 = 0.4$ )



(d) high-density random networks ( $p_1 = 0.8$ )

5,000  
iterations for  
each  
benchmark  
instance.

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# Conclusion and Future Work

- Conclusion
  - We developed CCG-Max-Sum, a variant of the lifted min-sum message passing algorithm (Xu et al. 2017), for solving DCOPs.
  - We combined NT reduction with CCG-Max-Sum.
  - We experimentally showed the advantage of CCG-Max-Sum.
- Future Work
  - Investigate mixed soft and hard constraints
  - Incorporate Crown reduction (Chlebík et al. 2008)


# References I




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